# Implementation of an Algorithm on Converting Sums into Nested Sums 

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$$
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$$

Joint Work with Carsten Schneider of RISC


## Outlines

(1) BackGround \& Motivation

- A Quick Introduction on Nested Sums
- Sigma.m Package of RISC
(2) The Algorithm [C. Anzai \& Y. Sumino]
- Steps of the Algorithm
- Problems.
(3) Conclusion


## Nested Sums

## Definition

An indefinite nested sum usually has the form

$$
\begin{aligned}
S(\nu) & =\sum_{\substack{\Lambda(\nu) \geq j_{1} \geq j_{2} \geq \cdots \geq j_{n} \geq 1}} f_{1}\left(j_{1}\right) f_{2}\left(j_{2}\right) \ldots f_{n}\left(j_{n}\right) . \\
& =\sum_{j_{1}=1}^{\Lambda(\nu)} f_{1}\left(j_{1}\right) \sum_{j_{2}=1}^{j_{1}} f_{2}\left(j_{2}\right) \ldots f_{n-1}\left(j_{n-1}\right) \sum_{j_{n}=1}^{j_{n-1}} f_{n}\left(j_{n}\right)
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\end{aligned}
$$

## Example

$$
\sum_{j_{1}=0}^{m} \sum_{j_{2}=0}^{j_{1}} \cdots \sum_{j_{n}=0}^{j_{n-1}} 1=\binom{m+n}{n}
$$

## Nested Sums Continued

## Examples

$$
\left\{\begin{array}{l}
Z\left(n ; m_{1}, \ldots m_{k} ; x_{1}, \ldots, x_{k}\right):=\sum_{n \geq i_{1}>\cdots>i_{k}>0^{\frac{i_{1}}{i_{1}}} \ldots \frac{x_{k}^{i_{1}}}{i_{k}^{i_{k}}}}^{i_{k}^{i_{k}}} \quad \text { Z-sum } \\
S\left(n ; m_{1}, \ldots m_{k} ; x_{1}, \ldots, x_{k}\right):=\sum_{n \geq i_{1} \geq \cdots \geq i_{k} \geq 1^{i_{1}}}^{\frac{x_{1}^{i_{1}}}{i_{1}^{i_{1}}} \ldots \frac{x_{k}^{i_{k}}}{i_{k}^{m_{k}}} \quad \text { S-sum }} \\
H\left(n ; a_{1}, \ldots, a_{k}\right):=\sum_{n \geq i_{1} \geq \cdots \geq i_{k} \geq 1} \frac{\operatorname{sign(a_{1})^{i_{1}}}}{i_{1}^{\left|a_{1}\right|}} \ldots \frac{\operatorname{sign}\left(a_{k}\right)^{i_{k}}}{i_{1}^{\left|a_{k}\right|}} \quad \text { H-sum }
\end{array}\right.
$$

## Remark



## Nested Sums Continued

## Examples

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\begin{aligned}
& \left(Z\left(n ; m_{1}, \ldots m_{k} ; x_{1}, \ldots, x_{k}\right):=\sum_{n \geq i_{1}>\cdots>i_{k}>0} 0_{1}^{\frac{x_{1}^{i_{1}}}{i_{1}}} \ldots \frac{x_{k}^{i_{k}}}{i_{k}^{k_{k}}} \quad\right. \text { Z-sum }
\end{aligned}
$$

## Remark

$$
\begin{array}{r}
Z(\infty ; s ; 1)=S(\infty ; s ; 1)=\sum_{i=1}^{\infty} \frac{1}{i s}=\zeta(s) \\
H(n ; 1)=\sum_{i=1}^{n} \frac{1}{i}=H_{n} ; H(n ; p(>o))=\sum_{i=1}^{n} \frac{1}{i p}
\end{array}
$$

BackGround \& Motivation

## Why "Nested" Sums



$$
S_{1}=S_{2}=: S(\nu)
$$

## Why "Nested" Sums

$$
S_{1}(\nu):=\sum_{x=1}^{\nu} \frac{1}{(x+\nu)^{2}}
$$



Fact

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\begin{gathered}
S_{1}(\nu):=\sum_{x=1}^{\nu} \frac{1}{(x+\nu)^{2}} \\
S_{2}(\nu):=\sum_{x=0}^{\nu-1}[\frac{1}{(1+2 x)^{2}}+\underbrace{\frac{1}{(2+2 x)^{2}}-\frac{1}{(1+x)^{2}}}_{=-\frac{3}{4(1+x)^{2}}}]
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## Fact

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## Why "Nested" Sums (Continued)

[Question]What is the asymptotic behavior of $S(\nu)$ ?

[Anwser]


## Reason I for Choosing Nested Sums

Asvmptotics.

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S_{1}(\nu):=\sum_{x=1}^{\nu} \frac{1}{(x+\nu)^{2}}[\text { VS }] S_{2}(\nu):=\sum_{x=0}^{\nu-1}\left[\frac{1}{(1+2 x)^{2}}-\frac{3}{4(1+x)^{2}}\right]
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## Convergence.

## Example

Theorem
$S(\infty)$ is convergent iff $m_{1}>1$ [provided that $S(\infty)$ has only finitely many sums]

## Why "Nested" Sums (Continued)

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## Convergence.

## Example

$$
S(\infty)=\sum_{i_{1}=1}^{\infty} \frac{\sum_{i_{2}=1}^{i_{1}} \frac{\sum_{i_{3}=1}^{i_{2}} \cdots}{i_{2}^{m_{2}}}}{i_{1}^{m_{1}}}
$$

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## Why "Nested" Sums (Continued)

## Reason III for Choosing Nested Sums

## "Algebraic Relations to Reduce the Sum".

> Remark
> This is what the "Sigma.m" package does. [A mathematica package that Carsten works on for years to deal with "all"(at least hypergeometric) sums/products]

## Algebraic Relations

In short, given a nested sum, we want to express it in terms of
known special functions, e.g. S-sums, Z-sums, $A F_{B}$, etc. Algebraic relations could help us to find the minimal basis for the expression and reduce the sum

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In short, given a nested sum, we want to express it in terms of known special functions, e.g. S-sums, Z-sums, $A_{A} F_{B}$, etc. Algebraic relations could help us to find the minimal basis for the expression and reduce the sum.

## Sigma.m Package

"Sigma is a Mathematica package that can handle multisums in terms of indefinite nested sums and products. The summation principles of Sigma are: telescoping, creative telescoping and recurrence solving. The underlying machinery of Sigma is based on difference field theory. The package has been developed by Carsten Schneider, a member of the RISC Combinatorics group.
"The source code for this package is password protected. To get the password send an email to Peter Paule. It will be given for free to all researchers and non-commercial users.
Copyright (C) 1999-2012 The RISC Combinatorics Group, Austria - all rights reserved. Commercial use of the software is prohibited without prior written permission.

## http://www.risc.jku.at/research/combinat/software/Sigma/index.php

## Sigma.m Package (Continued)

In short, "Sigma.m" deals with general multisums.

The algorithm I am working on deals with special case.

## Form of the Required Sums

$$
S(\nu)=\sum_{i_{1}=a_{1}(\nu)}^{\sum_{i_{2}}=a_{2}\left(\nu, i_{1}\right)} \sum_{i_{n}=a_{n}\left(\nu, i_{1}, \ldots i_{n-1}\right)}^{b_{2}\left(\nu, i_{1}\right)} \sum_{r}^{b_{n}\left(\nu, i_{1} \ldots, i_{n-1}\right)} \frac{\lambda_{1}^{i_{1}} \ldots \lambda_{n}^{i_{n}}}{L_{r}\left(\nu, i_{1}, \ldots, i_{n}\right)^{p_{r}}}
$$

where
$\left(\lambda_{k} \in \mathbb{C}\right.$
$p_{k} \in \mathbb{N}=\{1,2, \ldots\}$
$L_{r}$ is a linear polynomial with integer coefficients
$a_{k}, b_{k}$ are either infinity or linear polynomials with integer coefficients

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$$

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NOTE: The number of products in the denominator is unknown.

## Examples

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$\sum_{k=1}^{\infty} \sum_{m=1}^{\infty} \frac{1}{(k+m)^{2}(2 m+4 k+1)}=4-2 \mathcal{C} \pi-\frac{\pi^{2}}{6}-4 \log 2+\frac{21}{4} \zeta(3)$.
$\sum_{k=1}^{\infty} \sum_{m=1}^{k} \frac{(-1)^{k+m}}{(k+1)^{2}(2 m+1)}=8 \operatorname{lm}[Z(\infty ; 2,1 ;-i, i)]+4 \mathcal{C} \log 2-\frac{\pi^{3}}{8}-\frac{\pi^{2}}{12}$.
Where, $\mathcal{C}=\sum_{k=0}^{\infty} \frac{(-1)^{k}}{(2 k+1)^{2}}$-Catalan Constant

## An Important Notation

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\sum_{k=a}^{b} f(k)= \begin{cases}\sum_{k=a}^{b} f(k) & a \leq b \\ 0 & a=b+1 \\ -\sum_{k=b+1}^{a-1} f(k) & a \geq b+2\end{cases}
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$$

## Example

$$
\sum_{x=5}^{2} x=-\sum_{x=3}^{4} x=-7
$$

## Key Idea_-Invariant under Shifting

Find a set of integers $\left(\Delta_{0}, \Delta_{1}, \ldots, \Delta_{n}\right)$, s.t.
(1) $\Delta_{0} \neq 0$
(2) $\forall r$,

$$
L_{r}\left(\nu+\Delta_{0}, i_{1}+\Delta_{1}, \ldots, i_{n}+\Delta_{n}\right)=L_{r}\left(\nu, i_{1}, \ldots, i_{n}\right) .
$$

[Question] Does such an integer vector always exist? [Answer] No. For example, when the number of $L_{r}$ 's is larger than the number of sums.

## Example



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Example

$$
S(\nu)=\sum_{m=0}^{\infty} \frac{1}{(\nu+m)^{2}(4 \nu+2 m+1)} .
$$

## Step I—Partial Fraction Decomposition(PFD)

## Step 1—Partial Fraction Decomposition(PFD)

## KEY: From the Innermost Sum Index to the Outermost

## Example

## Result

For each part of the sum, the number of $L_{r}$ 's is NO GREATER THAN the number of sums, i.e. it guarantees the existence of the invariant shifting vector $\left(\Delta_{0}, \Delta_{1}, \ldots, \Delta_{n}\right)$
$\square$
NOTE
The solution $\left(\Delta_{0}, \Delta_{1}, \ldots, \Delta_{n}\right)$ has at least one free variable to turn rational solutions into integer solutions.

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\sum_{x \geq y \geq z} \frac{1}{(x+y)(y+z)(x+z)}=\sum_{x \geq y \geq z} \frac{1}{2 x}\left[\frac{1}{x+y}+\frac{1}{x-y}\right]\left[\frac{1}{y+z}-\frac{1}{x+z}\right]
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## NOTE

The solution ( $\Delta_{0}, \Delta_{1}, \ldots, \Delta_{n}$ ) has at least one free variable to turn rational solutions into integer solutions.

Steps of the Algorithm Problems.

## Step II——Key Step (Idea)

For a (not completely known) function $f(x)$, suppose we want to compute $f(101)$, by knowing the following

$$
\left\{\begin{array}{l}
f(2) \\
\Delta f(x):=f(x+3)-f(x)
\end{array}\right.
$$

Noting that

$$
\begin{aligned}
& 101 \equiv 2(\bmod 3) \\
f(101) & =f(98)+[f(101)-f(98)] \\
& =f(98)+\Delta f(98) \\
& =\cdots \\
& =f(2)+\sum_{k=0}^{32} \Delta f(3 k+2) .
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Now, we could consider

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## Define


and


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Define

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\lambda:=\prod_{k=1}^{n} \lambda_{k}^{\Delta_{k}}
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$$

Define

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\lambda:=\prod_{k=1}^{n} \lambda_{k}^{\Delta_{k}}
$$

and

$$
\Delta S(\nu):=S\left(\nu+\Delta_{0}\right)-\lambda S(\nu)
$$

## Step II——Key Step(Continued)

Define

$$
\left\{\begin{array}{l}
\alpha_{k}:=a_{k}\left(\nu+\Delta_{0}, i_{1}+\Delta_{1}, \ldots, i_{k-1}+\Delta_{k-1}\right)-a_{k}\left(\nu, i_{1}, \ldots, i_{k-1}\right) \in \mathbb{Z} \\
\beta_{k}:=b_{k}\left(\nu+\Delta_{0}, i_{1}+\Delta_{1}, \ldots, i_{k-1}+\Delta_{k-1}\right)-b_{k}\left(\nu, i_{1}, \ldots, i_{k-1}\right) \in \mathbb{Z}
\end{array} .\right.
$$

Then

## $S\left(\nu+\Delta_{0}\right)$



## Step II——Key Step(Continued)

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\end{array} .\right.
$$

Then

$$
\begin{aligned}
S\left(\nu+\Delta_{0}\right) & =\sum_{i_{1}=a_{1}\left(\nu+\Delta_{0}\right)}^{b_{1}\left(\nu+\Delta_{0}\right)} \ldots \sum_{i_{n}=a_{n}\left(\nu+\Delta_{0}, i_{1}, \ldots i_{n-1}\right)}^{b_{n}\left(\nu+\Delta_{0}, i_{1} \ldots, i_{n-1}\right)} \frac{\lambda_{1}^{i_{1}} \ldots \lambda_{n}^{i_{n}}}{\prod_{r=1}^{n} L_{r}\left(\nu+\Delta_{0}, i_{1}, \ldots, i_{n}\right)^{p_{r}}} \\
{\left[i_{k} \mapsto i_{k}+\Delta_{k}\right] } & =\sum_{i_{1}+\Delta_{1}=a_{1}+\alpha_{1}}^{b_{1}+\beta_{1}} \ldots \sum_{i_{n}+\Delta_{n}=a_{n}+\alpha_{n}}^{b_{n}+\beta_{n}} \frac{\lambda_{1}^{i_{1}+\Delta_{1}} \ldots \lambda_{n}^{i_{n}+\Delta_{n}}}{\prod_{r=1}^{n} L_{r}\left(\nu+\Delta_{0}, i_{1}+\Delta_{1}, \ldots, i_{n}+\Delta_{n}\right)^{p_{r}}} \\
& =\lambda \sum_{i_{1}=a_{1}+\alpha_{1}-\Delta_{1}}^{b_{1}+\beta_{1}-\Delta_{1}} \ldots \sum_{i_{n}=a_{n}+\alpha_{n}-\Delta_{n}}^{b_{n}+\beta_{n}-\Delta_{n}} \underbrace{\prod_{r=1}^{n} L_{r}\left(\nu+\Delta_{0}, i_{1}, \ldots, i_{n}\right)^{p_{r}}}_{\text {su:= }}
\end{aligned}
$$

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\Delta S(\nu) & =S\left(\nu+\Delta_{0}\right)-\lambda S(\nu) \\
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Steps of the Algorithm Problems.

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$$

## Step II——Key Step(Continued)

Suppose $\nu_{0} \in\left\{0,1, \ldots, \Delta_{0}\right\}$, s.t. $\nu \equiv \nu_{0}\left(\bmod \Delta_{0}\right)$, then

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## [Question] How to deal with $S\left(\nu_{0}\right)$ ?

## FACT(Good News)

## $\nu_{0} \in\left\{0,1, \ldots, \Delta_{0}\right\} \Rightarrow S\left(\nu_{0}\right)$ is determined.

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Multipling by a Projector and Adding a definite sum:


Rewriting the Inner Sum Range and Symplifying


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Multipling by a Projector and Adding a definite sum:
$S(\nu)=\sum_{\mu_{0}=0}^{\Delta_{0}-1} \operatorname{Proj}\left(\nu, \mu_{0}, \Delta_{0}\right)\left[\lambda^{\frac{\nu-\mu_{0}}{\Delta_{0}}} S\left(\mu_{0}\right)+\sum_{\mu=\mu_{0}}^{\nu-\Delta_{0}} \operatorname{Proj}\left(\mu, \mu_{0}, \Delta_{0}\right) \Delta S(\mu) \lambda^{\frac{\nu-\mu-\Delta_{0}}{\Delta_{0}}}\right]$.
Rewriting the Inner Sum Range and Symplifying


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## Example

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& -\sum_{x=0}^{\nu-1} \sum_{y=0}^{x-1} \frac{1}{x+3}\left[\frac{1}{y+1}+\frac{1}{y+3}\right] \\
& +\sum_{x=0}^{\nu-1} \sum_{y=0}^{x-1} \frac{1}{2 x+5}\left[\frac{1}{y+1}+\frac{1}{2 y+5}\right]
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## Advantages of the Algorithm

## Speed.

This is the reason for Carsten to have interest in this algorithm.

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## Steps of the Algorithm

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$$
\left\{\begin{array}{l}
\operatorname{Proj}(m, n, 1) \equiv 1 \\
\operatorname{Proj}(m, n, 2)=\frac{(-1)^{m}+(-1)^{n}}{2}
\end{array}\right.
$$

## When $d \geq 3$, root of unity is inevitable.

## Example

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\operatorname{Proj}(6,2,3)=\frac{\frac{1}{3}\left(1+e^{-\frac{2 \pi i}{3}}+e^{\frac{2 \pi i}{3}}\right)}{\text { Mathematica }}=0
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## Problem II——Root of Unity (Continued)

## FACT <br> There is no other substitutions for the projector function.

## Solutions/Compromise

(3) Try to make $\Delta_{0}$ as small as possible. ( $\Delta_{0}=1$ or $\left.\Delta_{0}=2\right)$
(2) "Replacement $\nu \mapsto \Delta_{0} \nu$ ". (Conditionally)

We can only make such replacement for the outermost sum.

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## Problem III——Poles

## FACT

It is very common when converting sums into nested sums.

## Example

[Created by PFD]

$\bar{S}(1)$

## Problem III_—Poles

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## Example

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$$
S(\nu)=\sum_{x=1}^{\nu} \frac{1}{(\nu+x)(x+1)} \Rightarrow S(1)=\frac{1}{4}
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## Problem III——Poles

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[Created by PFD]

$$
\begin{aligned}
& S(\nu)=\sum_{x=1}^{\nu} \frac{1}{(\nu+x)(x+1)} \Rightarrow S(1)=\frac{1}{4} \\
& \bar{S}(\nu)= \sum_{x=1}^{\nu}\left[\frac{1}{(\nu-1)(\nu+x)}-\frac{1}{(\nu-1)(x+1)}\right] \\
&= \frac{1}{\nu-1} \sum_{x=0}^{\nu-1}\left[\frac{1}{x+2}+\frac{1}{x+1}-\frac{1}{2 x+1}-\frac{1}{2 x+2}\right] \\
& \bar{S}(1) \quad=\quad \frac{0}{0}=\text { 'Indetermined" }
\end{aligned}
$$

## Problem III——Poles (Continued)

## Example

[Created by Shifting (Crossing the Boundary)]

$$
S(\nu)=\sum_{x=1}^{\nu} \sum_{z=1}^{x-1} \frac{1}{(\nu+x+1)(x+z)} .
$$

Note:

$$
\Delta_{0}=1, \Delta_{x}=\Delta_{1}=-1, \Delta_{z}=\Delta_{2}=1 .
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Fact
While computing $\Delta S(\nu)$, the following sum appears

## Problem III——Poles (Continued)

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\sum_{x=1}^{\nu} \sum_{z=(x-1)+1}^{(x-1)+(-1)-1} \frac{1}{(\nu+x+1)(x+z)}=-\sum_{x=1}^{\nu}\left[\frac{1}{(\nu+x+1)(2 x-1)}+\frac{1}{(\nu+x+1)(2 x-2)}\right],
$$

## Dealing with Poles—by Authors

## Remark

In the paper, during Step II, when poles/divergence terms are created, they introduce regularization parameter, by $i_{k} \mapsto i_{k}+\delta_{k}$. Also, the paper talks about Step III, evaluation, which one can eventually send $\delta_{k} \rightarrow 0$.

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## FACT

The speed will be slowed down dramatically by introducing more parameters, which violates our original purpose for implementation.

## Dealing with Poles-Modifying the Starting Point

[Q]:Recall the expression

and suppose $\Delta S(\mu)$ has a pole at $\mu=1$. How to deal with it? RECALL


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\begin{aligned}
f(101) & =f(2)+\sum_{k=0}^{32} \Delta f(3 k+2) \\
& =f(5)+\sum_{k=1}^{32} \Delta f(3 k+2) \\
& =\ldots
\end{aligned}
$$

## Dealing with Poles-Modifying the Starting Point

[Q]:Recall the expression

$$
S(\nu)=\lambda^{\frac{\nu}{\Delta_{0}}} \sum_{\mu_{0}=0}^{\Delta_{0}-1} \operatorname{Proj}\left(\nu, \mu_{0}, \Delta_{0}\right)\left[\lambda^{-\frac{\mu_{0}}{\Delta_{0}}} S\left(\mu_{0}\right)+\sum_{\mu=0}^{\nu-1} \operatorname{Proj}\left(\mu, \mu_{0}, \Delta_{0}\right) \Delta S(\mu) \lambda^{-\frac{\mu+\Delta_{0}}{\Delta_{0}}}\right],
$$

and suppose $\Delta S(\mu)$ has a pole at $\mu=1$. How to deal with it? RECALL

$$
\begin{aligned}
f(101) & =f(2)+\sum_{k=0}^{32} \Delta f(3 k+2) \\
& =f(5)+\sum_{k=1}^{32} \Delta f(3 k+2) \\
& =\ldots
\end{aligned}
$$

## Dealing with Poles-Modifying the Starting Point (Continued)

## KEY <br> Find $k \in \mathbb{N}$, s.t. $k \cdot \Delta_{0}>1$ (the largest pole of $\left.\Delta S(\mu) \& S\left(\nu_{0}\right)\right)$

Corresponding Expression

## Dealing with Poles-Modifying the Starting Point (Continued)

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## Corresponding Expression

$S(\nu)=\lambda^{\frac{\nu}{\Delta_{0}}} \sum_{\mu_{0}=0}^{\Delta_{0}-1} \operatorname{Proj}\left(\nu, \mu_{0}, \Delta_{0}\right)\left[\lambda^{-\frac{\mu_{0}}{\Delta_{0}}-k} S\left(\mu_{0}+k \cdot \Delta_{0}\right)+\sum_{\mu=k \Delta_{0}}^{\nu-1} \operatorname{Proj}\left(\mu, \mu_{0}, \Delta_{0}\right) \Delta S(\mu) \lambda^{-\frac{\mu+\Delta_{0}}{\Delta_{0}}}\right]$

## Dealing with Poles-Splitting the Sums

## Example



## Dealing with Poles-Splitting the Sums

## Example

$$
\begin{aligned}
S(\nu) & :=\sum_{x=1}^{\nu} \sum_{y=1}^{x} \frac{1}{(x+y)(y+1)} \\
& =\sum_{x=1}^{\nu} \sum_{y=1}^{x}\left[\frac{1}{(x-1)(x+y)}-\frac{1}{(x-1)(y+1)}\right]
\end{aligned}
$$

## Dealing with Poles-Splitting the Sums

## Example

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& =\sum_{x=1}^{\nu} \sum_{y=1}^{x}\left[\frac{1}{(x-1)(x+y)}-\frac{1}{(x-1)(y+1)}\right] \\
& \left\{\begin{array}{l}
S_{1}(\nu)=\left.\sum_{x=1}^{\nu} \sum_{y=1}^{x} \frac{1}{(x+y)(y+1)}\right|_{x=1}=\frac{1}{4} \\
S_{2}(\nu)=\sum_{x=2}^{\nu} \sum_{y=1}^{x} \frac{1}{(x+y)(y+1)}
\end{array}\right.
\end{aligned}
$$

## Conclusion

## Conclusions/Experience

(1) This algorithm works faster than the usual/general method of Sigma.m.
(2) Root of unity is inherited from the algorithm. It seems to be impossible to avoid.

3 Poles are very common while converting sums (creating telescoping). And the poles created by PFD is easier to deal with comparing to those from shifting.
4 Adding regularization parameters will slow down this algorithm dramatically.

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## THE END

## Thank you!


[^0]:    Solution

[^1]:    FACT
    The speed will be slowed down dramatically by introducing more
    parameters, which violates our original purpose for implementation

[^2]:    FACT
    The speed will be slowed down dramatically by introducing more parameters, which violates our original purpose for implementation

